

ALGORITHMS THAT KNOWBACK

COMP 210 – 04 NOV 2005

(P)REVIEW

- **All the way back to Lecture 14 (9/28)**
- **Descendant family trees**

blue-eyed-descendant?

➤ Data definition:

```
(define-struct parent (children name date eyes))
```

```
:: A parent is (always!) a structure:
```

```
:: (make-parent loc n d e)
```

```
:: where loc is a list of children, n and e
```

```
:: are symbols, and d is a number.
```

```
:: A list-of-children is either
```

```
:: 1. empty or
```

```
:: 2. (cons p loc) where p is a parent and loc is
```

```
:: a list of children.
```

blue-eyed-descendant?

```
;; blue-eyed-descendant? : parent -> boolean  
;; to determine whether a-parent any of the descendants (children,  
;; grandchildren, and so on) have 'blue in the eyes field
```

```
(define (blue-eyed-descendant? a-parent)  
  (cond  
    [(symbol=? (parent-eyes a-parent) 'blue) true]  
    [else (blue-eyed-children? (parent-children a-parent))]))
```

```
;; blue-eyed-children? : list-of-children -> boolean  
;; to determine whether any of the structures in aloc is blue-eyed  
;; or has any blue-eyed descendant
```

```
(define (blue-eyed-children? aloc)  
  (cond  
    [(empty? aloc) false]  
    [(blue-eyed-descendant? (first aloc)) true]  
    [else (blue-eyed-children? (rest aloc))]))
```

BACKTRACKING

- The book devotes a whole section to this
- A common technique when searching trees
 1. Go down one branch
 2. if you don't find the answer, go down the next branch
- This applies to a more general class of tree-like structures, called

GRAPHS

[YOU'LL SEE THESE AGAIN AND AGAIN]

DIRECTED GRAPHS, FORMALLY

- A *directed graph* $G = \{ V, E \}$
 - V : a set of vertices
 - E : a set of edges
- An edge is a pair of vertices $\{ V_1, V_2 \}$
 - The edge connects V_1 to V_2
- We interpret these sets as a picture in which vertices are connected to one another by edges

TREES?

- Trees are graphs, too
 - With the added restriction that each vertex may have exactly one edge leading to it
 - We call the number of inbound edges “in-degree”, so trees are directed graphs of in-degree 1

EXAMPLES OF DIRECTED GRAPHS

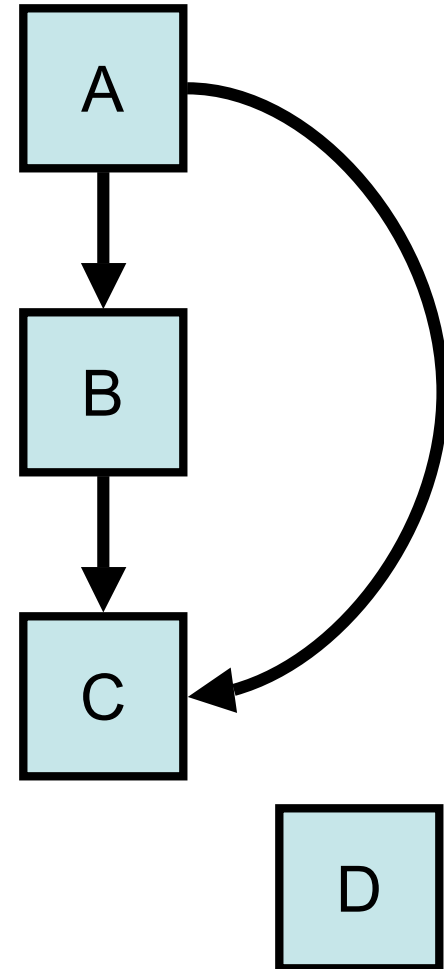
- The Web: a page has potentially many links to another page
- The Internet: computers connected to other computers (it seems like it might be undirected, but consider a firewall: things can go out, but not back in)
- Downtown Houston: one-way streets, and some streets don't connect
- Facebook, MySpace, Friendster, Orkut, etc. (linking people to each other, in a DIRECTED fashion)

REPRESENTING GRAPHS

- We choose Scheme lists
- A node (“vertex”) is a symbol, like 'A
- A graph is
 - a *list of*
 - (list node (listof nodes))
 - We call this an “associative list”
- The (listof nodes) represents the nodes reachable from that node

EXAMPLE

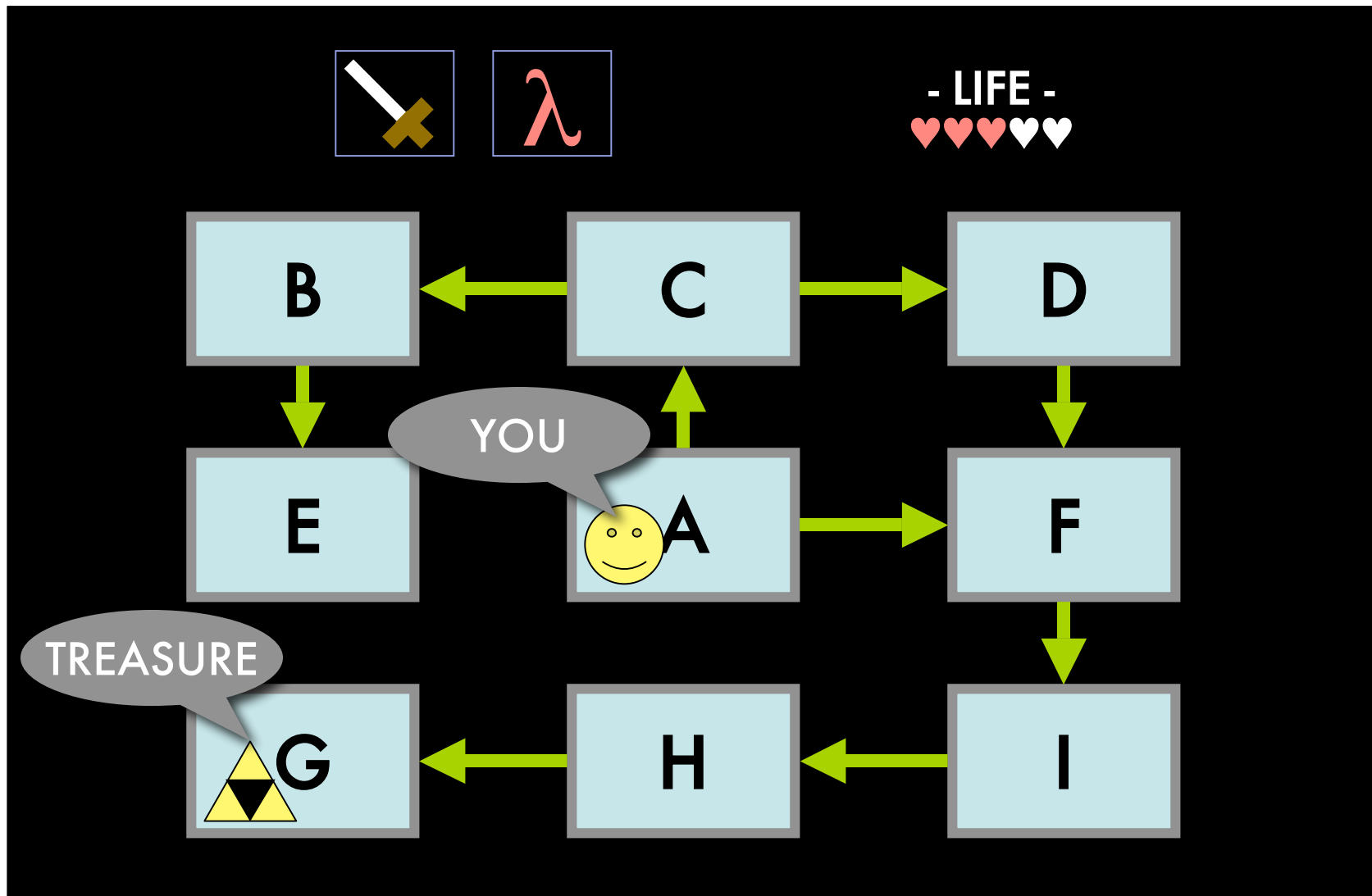
```
(define Graph  
  (list  
    (list 'A (list 'B 'C))  
    (list 'B (list 'C))  
    (list 'C empty)  
    (list 'D empty)))
```



PROBLEM: ROUTE SEARCH

- We want to find a route from one node to another.
 - (Maybe this is a maze in which you have a starting point, a number of one-way paths, and a goal.)

EXAMPLE



THIS TIME, IN SCHEME

(define Graph

'[(A (C F))

(B (E))

(C (D B))

(D (F))

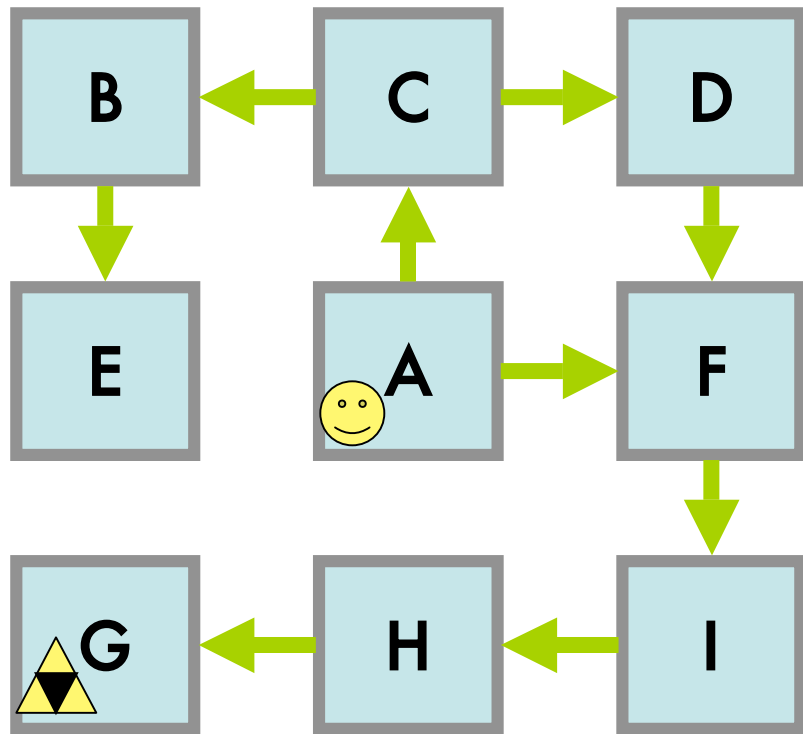
(E ())

(F (I))

(G ())

(H (G))

(I (H)))]



OUR GOAL: find-route

`:: find-route : node node graph -> [node]`

`:: find a path from a to b in graph g`

`(define (find-route a b g) ...)`

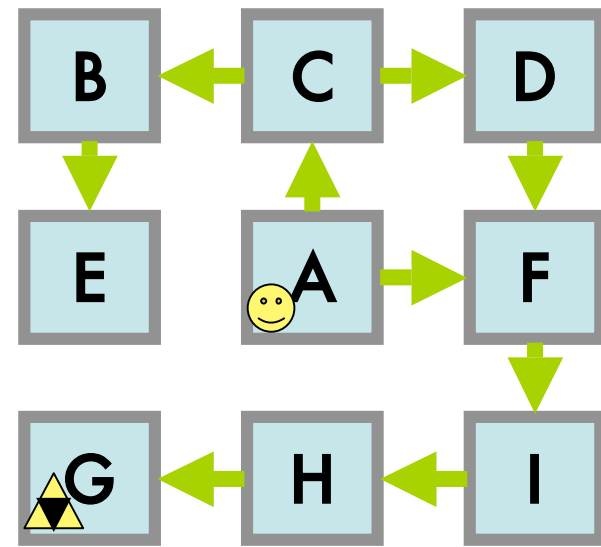
`:: examples`

`(find-route 'A 'A Graph)`

`=> (list 'A)`

`(find-route 'A 'B Graph)`

`=> (list 'A 'C 'B)`

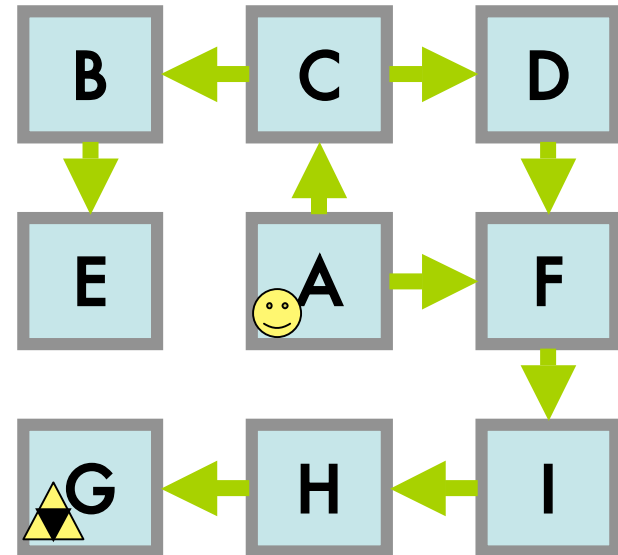


PATHS MIGHT NOT EXIST

(find-route 'D 'A G)

=> ?

- We need to expand our function's return type slightly to encode this



UPDATED: find-route

`:: find-route : node node graph -> [node] or false`

`:: find a path from a to b in graph g`

`:: if no path exists, returns false`

`(define (find-route a b g) ...)`

SOLVING A RECURSIVE PROBLEM

1. What's the **trivial problem** (the one we know how to solve right away)?
2. What's the trivial problem's **solution**?
3. How do we **break** a non-trivial problem up into **smaller problems**?
4. How do we **combine** the results?

ANSWERS TO THESE QUESTIONS AND MORE

1. The trivial problem:
if (symbol=? a b), we're done.
2. The path in this case is
(list b).
3. Otherwise,
inspect each neighbor of a and see if there exists
a path to b from it.
4. If we do find a path from a neighbor,
prepend our current node (cons a path) and return.

FIRST ATTEMPT: find-route

`:: find-route : node node graph -> [node] or false`

```
(define (find-route a b g)
```

```
  (cond
```

```
    [(symbol=? a b) (list b)]
```

```
    [else ... now what?
```

find-route (2)

;; find-route : node node graph -> [node] or false

```
(define (find-route a b g)
  (cond
    [(symbol=? a b) (list b)]
    [else (local
      [(define possible-route
          (find-route/list (neighbors a g) b g))]
        (cond
          [(cons? possible-route)
           (cons a possible-route)]
          [else false]))]))
```

TODO:
write find-route/list
and neighbors

TODO: find-route/list

- We said that, given a list of nodes, it should find a path (if it exists) from any of them
 - This is just like (blue-eyed-children?), remember?
 - We had (blue-eyed-descendant?) for one *ftn*, but needed a helper to look through a list of children

```
:: blue-eyed-descendant? : parent -> boolean
```

```
(define (blue-eyed-descendant? a-parent) ...)
```

```
:: blue-eyed-children? : list-of-children -> boolean
```

```
(define (blue-eyed-children? aloc) ...)
```

find-route/list (2)

;; find-route/list : [node] node graph -> [node] or false
;; finds the route in g, if it exists, from some node in l
;; to b; if no path exists, returns false

```
(define (find-route/list l b g)
  (cond
    [(empty? l) false]
    [else ... (find-route (first l) b g) ...
             ... (find-route/list (rest l) b g) ... ]))
```

find-route/list (3)

;; find-route/list : [node] node graph -> [node] or false

```
(define (find-route/list l b g)
  (cond
    [(empty? l) false]
    [else (local
              [(define possible-route
                 (find-route (first l) b g))]
              (cond
                [(cons? possible-route) possible-route]
                [else (find-route/list (rest l) b g)]))]))))
```


ONE LAST TODO

```
;; neighbors: node graph -> [node]
;; finds the nodes in g reached by edges from n
(define (neighbors n g)
  (cond
    [(empty? g) (error 'neighbors "Not in graph!")]
    [else (cond
              [(symbol=? n (first (first g)))
               (second (first g))]
              [else (neighbors n (rest g))])])))
```

TIME EXTENDED!

➤ Seriously, we have time left over?

(cond

[(find-routes-in-cyclic-graphs?) (go)]

[(learn-about-associative-lists?) (go)])

ASSOCIATIVE LISTS

- These things are fun
- Use them to organize data by “name”
- Type: [(list X ?)]
- Example:

```
(define too-many-dans (list  
  (list 'dsandler "Dan Sandler")  
  (list 'dlsmith "Dan Smith")  
  (list 'danvk "Dan Vanderkam")))
```

FUNCTIONS FOR ASSOCIATIVE LISTS

- You could write your own, like (neighbors), but Scheme gives us the most abstract one:

```
;; assf : (X -> boolean) [(list X ...)] -> ?
```

```
;; (an unfortunate name)
```

```
;; if there exists a (list x ...) in the associative list
```

```
;; al return the second of the list; otherwise false
```

```
(define (assf func al)
```

```
  (cond
```

```
    [(empty? al) false]
```

```
    [else (cond
```

```
      [(func (first (first al))) (second (first al))]
```

```
      [else (assf func (rest al))]))]))
```

EXEMPLI GRATIA

```
(assf (lambda (x) (symbol=? x 'dsandler))  
      too-many-dans)  
⇒ "Dan Sandler"
```

```
(assf (lambda (x) (symbol=? x 'dwallach))  
      too-many-dans)  
⇒ false
```

- › There are others, too
 - › ...shorthands for "look in the assoc. for something 'equal' to x"
 - › To define these requires knowledge of Scheme's weird equivalence functions
 - › (Of these, you've probably already seen equal? ... it gets weirder from there)

BACK TO GRAPHS

- How would we write (neighbors) with assf?

`; neighbors : node graph -> [node]`

`(define (neighbors n g)`

`(assf (lambda (x) (symbol=? x n)) g))`

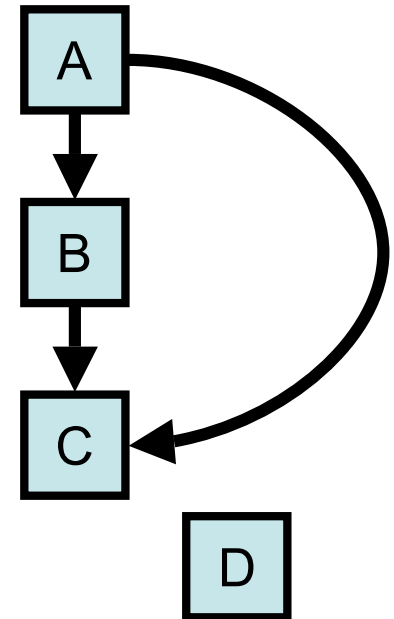
- (Easy!)

ONE LAST NOTE

- Prof. Taha points out: "If you know the entire graph ahead of time, why not just write that into the function?"

```
(define (graph1-neighbors n)
  (cond [(symbol=? n 'A) '(B C)]
        [(symbol=? n 'B) '(C)]
        [(symbol=? n 'C) '()]
        [(symbol=? n 'D) '()]
        [else (error ...)]))
```

- Each new (?-neighbors) function you write represents a different graph
- Our graph data definition becomes a *function*. Crazy!



GRAPHS WITH CYCLES

- We're time-travelling to next week's lectures, now
- If we ran (find-route) on a *cyclic* directed graph, what might happen?
 - Try it.
- How does this violate the recursive algorithm design?
 - Problem doesn't necessarily get smaller at every step!

I DON'T NEED TO WALK AROUND IN CIRCLES

- If only we had some way to remember which nodes we've already seen...
 - Maybe we can pass that information from function call to function call.
 - We call this kind of recursion "accumulation"—we're accumulating data as we dig deeper into the problem, as well as potentially creating data on our way back "out"

ACCUMULATION: A CRASH COURSE

› Old-school:

```
; sum: [num] -> num
(define (sum l)
  (cond
    [(empty? l) 0]
    [else
     (+ (first l)
        (sum (rest l)))]))
```

(sum (list 1 2 3 4)) => 10

› New-school:

```
; asum: [num] num -> num
(define (asum l a)
  (cond
    [(empty? l) a]
    [else
     (sum (rest l)
          (+ (first l) a))]))
```

(asum (list 1 2 3 4) 0) => 10

ACCUMULATING A LIST OF "SEEN" NODES

```
(define (route2 a b g seen)  
  (cond  
    [(symbol=? a b) (list a)]  
    [(in-list? a seen) false]  
    [else (local  
            [(define possible-route  
              (route2/list (neighbors a g) b g (cons a seen)))]  
            (cond  
              [(cons? possible-route) (cons a possible-route)]  
              [else false]))]))
```

Stop if we've
already
been here

```
(define (route2/list l b g seen)  
  (cond  
    [(empty? l) false]  
    [else (local  
            [(define possible-route (route2 (first l) b g seen))]  
            (cond  
              [(cons? possible-route) possible-route]  
              [else (route2/list (rest l) b g seen))]))]))
```

Add this node to
the "seen" list before
digging deeper

TESTING OUR NEW FUNCTION

```
(define G      > (route 'E 'G G)
  '[(A (B C D)) ...
    (B (C D))   user break
    (C (D))     > (route2 'E 'G G
    (D (E G))   empty)
    (E (A))     (list 'E 'A 'B 'C 'D 'G)
    (F ()))
  (G ()))])
```

= FIN =